

VIISNU ANAND S

ELECTRONICS AND COMMUNICATION ENGINEER

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SUMMARY

An enthusiastic Electronics and Communication Engineering student with a deep passion for technology and innovation. Skilled in embedded systems, with practical experience gained through academic projects and real-world applications. A proactive team player and fast learner with a problem-solving mindset, committed to continuous growth and eager to contribute meaningfully to engineering advancements and social development

EDUCATION

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|---|-------------|
| Kumaraguru College of Technology | 2022-2026 |
| B.E Electronics and Communication Engineering | |
| Higher Secondary Education (HSC) | 2020-2022 |
| Sri Chaitanya Techno School ,Salem | |
| Secondary School Education (SSLC) | 2018 - 2020 |
| Sri Chaitanya Techno School,Salem | |

INTERNSHIP

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| Pricol Limited (Corporate Manufacturing Engineering (CME) Department | June 2025 |
| <ul style="list-style-type: none">Worked on developing a low-cost wire colour sequence detection system using Jetson Orin Nano, Arducam, and OpenCV. Gained hands-on exposure to PLC automation, industrial R&D workflows, contributing to automation solutions in automotive manufacturing. | |

PROJECTS

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| Smart India Hackathon 2024–Winner of the Problem Statement (ISRO) |
| <ul style="list-style-type: none">Designed an AI-Powered DVB-S2X Signal Detection & Classification. Designed a real-time signal classification system for DVB-S2X waveforms. Utilized deep learning and SDR-based processing to detect and classify modulation types. <p>Technologies: ROS, ZED 2i, Jetson Orin Nano, Pixhawk, OpenCV, LiDAR, Python.</p> |
| IRoC-U 2025 (ISRO Robotics Challenge) |
| <ul style="list-style-type: none">Cleared the Elimination Round, ranking among the Top 37 teams in India, by developing an AI-driven UAV with SLAM, LiDAR, 3D vision, and sensor fusion for GNSS-denied navigation, precision mapping, and autonomous landing in Mars-like terrains. <p>Technologies: ROS, ZED 2i, Jetson Orin Nano, Pixhawk, OpenCV, LiDAR, Python.</p> |
| Wire Color Detection System (Internship Project) |
| <ul style="list-style-type: none">Designed a vision-based color sequence detection system for automotive wire harness verification. Achieved 35% inspection time reduction. Technologies: Jetson Orin Nano, OpenCV, Python <p>Technologies: ROS, ZED 2i, Jetson Orin Nano, Pixhawk, OpenCV, LiDAR, Python.</p> |
| Gesture-Controlled Robot – Mini Project |
| <ul style="list-style-type: none">Developed a Raspberry Pi-based robot controlled via real-time hand gestures using camera input. Implemented gesture recognition using OpenCV and MediaPipe with Flask-based wireless control. <p>Technologies: Raspberry Pi 4, Python, OpenCV, Flask.</p> |
| Surveillance Pi Bot – Mini Project |
| <ul style="list-style-type: none">Developed a live-streaming surveillance robot using Raspberry Pi and Pi Camera for remote monitoring applications. Implemented a Flask-based web interface for real-time video streaming and motion control. Integrated L298N motor driver for precise movement and efficient remote operation. <p>Technologies: Raspberry Pi 4, OpenCV, Flask, HTML/CSS, L298N Motor Driver</p> |

SOFT SKILLS

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|-------------------|-------------------|
| • Time Management | • Teamwork |
| • Leadership | • Problem Solving |

TECHNICAL SKILLS

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|--------------------|-----------------|
| • C Programming | • NVIDIA Boards |
| • Embedded Systems | • GNU Radio |

LANGUAGES KNOWN

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| • Tamil | • Hindi - Beginner Level |
| • English | • French - Beginner Level |

CERTIFICATIONS AND ACHIEVEMENTS:

Awards/Activities:

- Award for Extracurricular Excellence – Honored by KCT for contributions beyond academics.

Certifications:

- NPTEL Certification– Introduction to IoT
- Emerging Trends in IoT Cloud Computing (workshop)
- VLSI Essential Concepts and Detailed Interview Guide – Udemy